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Conditionally autoregressive model for spatial disaggregation of activity data in GHG inventory: Application for agriculture sector in Poland

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Development of spatial GHG inventory crucially depends on availability of *low resolution activity data*. In Poland, relevant information needs to be acquired from national/regional totals.

Goal

Application of **statistical spatial scaling methods** to produce higher resolution activity data



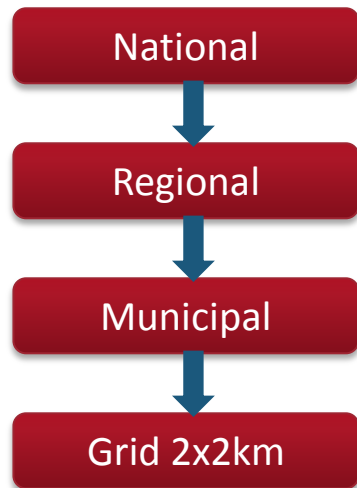
Classification of inventory sectors

Energy (fossil fuel burning)

- power/heat production
- residential
- transport
- industry and construction
- others

Industry (chemical processes)

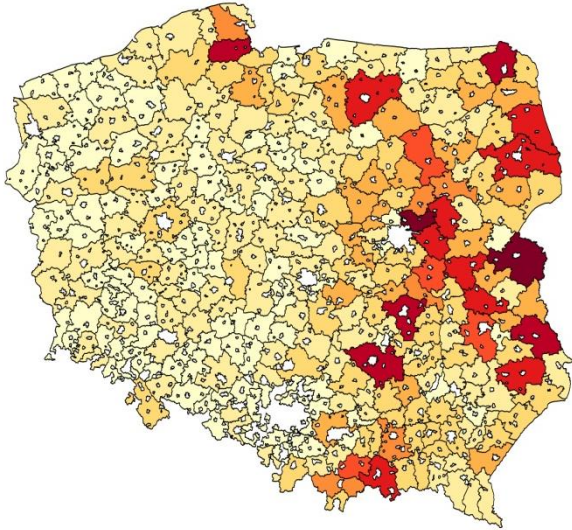
Agriculture



Disaggregation framework

Task

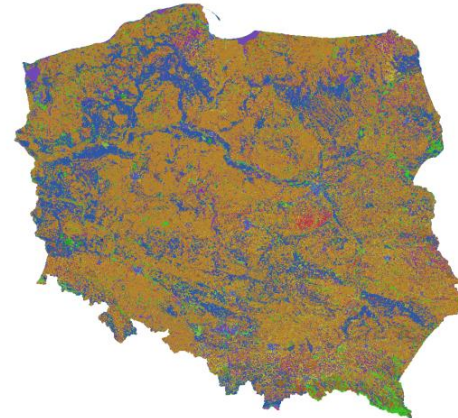
Livestock data available
in *disticts*



to be disaggregated
into *municipalities*,



making use of detailed
land cover map.



CAR model for areal data

- Conditionally autoregressive (CAR) formulation of process

$$\boldsymbol{\theta} = (\theta_1, \dots, \theta_n)^T$$

$$\theta_i \mid \theta_{j, j \neq i} \sim \text{Gau} \left(\rho \sum_{j \neq i} \frac{w_{ij}}{w_{i+}} \theta_j, \frac{\tau^2}{w_{i+}} \right), \quad i, j = 1, \dots, n$$

w_{ij} - neighbour weights: 1 for neighbour, 0 otherwise

$w_{i+} = \sum_j w_{ij}$ - number of neighbours of cell i

τ^2 - variance parameter

- Joint probability distribution of $\boldsymbol{\theta} = (\theta_1, \dots, \theta_n)^T$

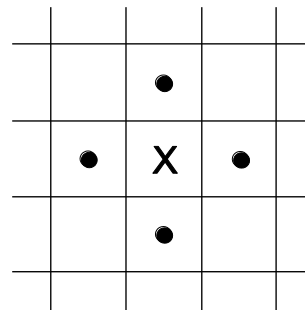
$$\boldsymbol{\theta} \sim \text{Gau}_n \left(\boldsymbol{\theta}, \tau^2 (\mathbf{D} - \rho \mathbf{W})^{-1} \right)$$

\mathbf{D} - a diagonal matrix with $[\mathbf{D}]_{ii} = w_{i+}$

$[\mathbf{W}]_{ij} = w_{ij}$ - a matrix with adjacency weights

τ^2 - a variance parameter

$$\tau^2 (\mathbf{D} - \rho \mathbf{W})^{-1} = \mathbf{N}$$



X - Cell i

• - Neighbours of cell i ($w_{ij} = 1$)

So, $w_{i+} = 4$

Disaggregation model → Specification in a *fine* grid

Y_i - random variable associated with emissions in a *fine* grid

$$Y_i | \mu_i \sim \text{Gau}(\mu_i, \sigma_Y^2), \quad i = 1, \dots, n$$

- Modelling $\boldsymbol{\mu} = (\mu_1, \dots, \mu_n)^T$

$$\boldsymbol{\mu} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\theta}, \quad \boldsymbol{\theta} \sim \text{Gau}_n(\mathbf{0}, \mathbf{N}) \quad (*)$$

available covariates
of cell i

spatial CAR
structure

\mathbf{X} - (design) matrix with covariates

$$\mathbf{N} = \tau^2 (\mathbf{D} - \rho \mathbf{W})^{-1}$$

→ Specification in a *coarse* grid

- The model for a *coarse* grid: multiplication of (*) with aggregation matrix $\mathbf{C}_{N \times n}$ indicating which cells are aligned together

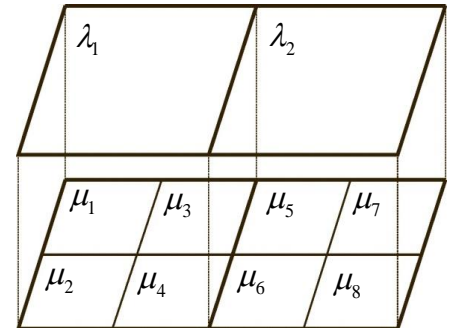
$$\mathbf{C}\boldsymbol{\mu} = \mathbf{C}\mathbf{X}\boldsymbol{\beta} + \mathbf{C}\boldsymbol{\theta} \quad \mathbf{C}\boldsymbol{\theta} \sim \text{Gau}_N(\mathbf{0}, \mathbf{C}\mathbf{N}\mathbf{C}^T)$$

N - # of observations in a *coarse* grid

n - # of observations in a *fine* grid

- $\boldsymbol{\lambda} = \mathbf{C}\boldsymbol{\mu}$ - the mean process for random variables $\mathbf{Z} = (Z_1, \dots, Z_N)^T$ of the *coarse* grid

$$\mathbf{Z} | \boldsymbol{\lambda} \sim \text{Gau}_N(\boldsymbol{\lambda}, \sigma_Z^2 \mathbf{I}_N)$$



Estimation

- The joint unconditional distribution of \mathbf{Z}

$$\mathbf{Z} \sim \text{Gau}_N(\mathbf{CX}\boldsymbol{\beta}, \mathbf{M} + \mathbf{CNC}^T)$$

where $\mathbf{M} = \sigma_Z^2 \mathbf{I}_N$, $\mathbf{N} = \tau^2 (\mathbf{D} - \rho \mathbf{W})^{-1}$

- Maximum likelihood estimation based on the joint distribution of \mathbf{Z} .
- Analytical solution for $\boldsymbol{\beta}$, further maximisation performed numerically.
- Expected Fisher information matrix used to get standard errors of parameters.

Prediction in a *fine* grid

- The process $\boldsymbol{\mu}$ underlying emission inventory is of our primary interest, with the optimal predictor given by $E(\boldsymbol{\mu}|\mathbf{z})$.
- The joint distribution of $(\boldsymbol{\mu}, \mathbf{Z})$

$$\begin{bmatrix} \boldsymbol{\mu} \\ \mathbf{Z} \end{bmatrix} \sim \text{Gau}_{n+N} \left(\begin{bmatrix} \mathbf{X}\boldsymbol{\beta} \\ \mathbf{CX}\boldsymbol{\beta} \end{bmatrix}, \begin{bmatrix} \mathbf{N} & \mathbf{NC}^T \\ \mathbf{CN} & \mathbf{M} + \mathbf{CNC}^T \end{bmatrix} \right)$$

which yield both the predictor $\hat{\boldsymbol{\mu}} = E(\boldsymbol{\mu} | \mathbf{z})$ and its error $\hat{\boldsymbol{\sigma}}_\mu^2 = \text{Var}(\boldsymbol{\mu} | \mathbf{z})$

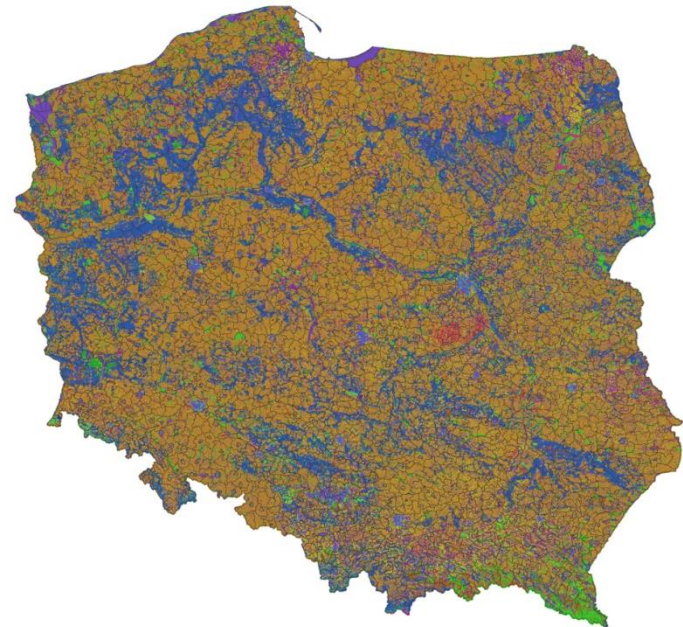
- The joint distribution of $(\boldsymbol{\mu}, \mathbf{Z})$ allows us to see the approach in analogy to *block kriging*.

Case study

- **Livestock** (cattle, pigs, horses etc.) data based on agricultural census 2010
 - Disaggregation from 314 districts (*powiaty*) into 2171 municipalities (*gminy*) needed
 - Only **rural municipalities** considered
- For **horses**, data are available also in municipalities, which enabled verification of the method.

Explanatory variables

- **Population**
- **Considered CORINE classes**
 - Pastures (231)
 - Complex cultivation patterns (242)
 - Principally agriculture, with natural vegetation (243)

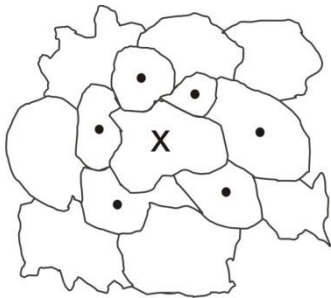


For each municipality, we calculate the area of these land use classes, that can be related to livestock farming.

Livestock data available in *districts*

Fit model **CAR**
Prediction in *municipalities*

Regression & spatial effect



Fit model **LM**
Prediction in *municipalities*

Regression based on
population & land use
No spatial effect

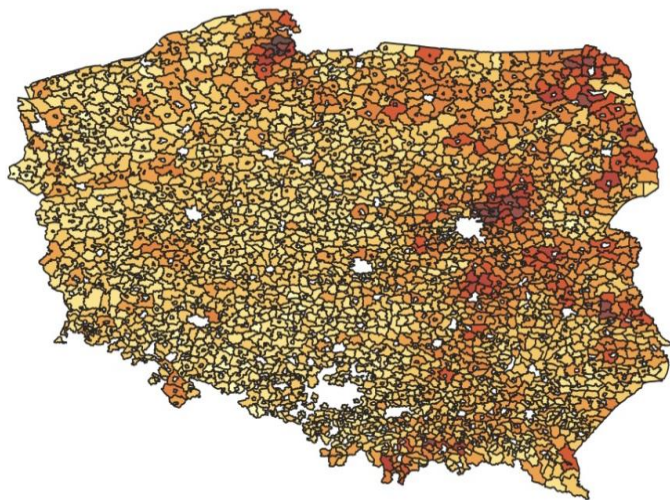
Fit model **NAIVE**
Prediction in *municipalities*

Solely in proportion
to population

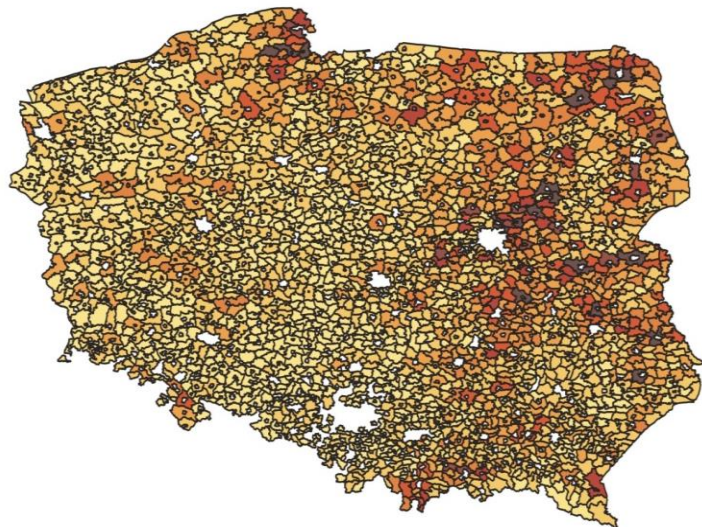
VERIFICATION: Data on horses available in *municipalities*

Results: Prediction for *municipalities*

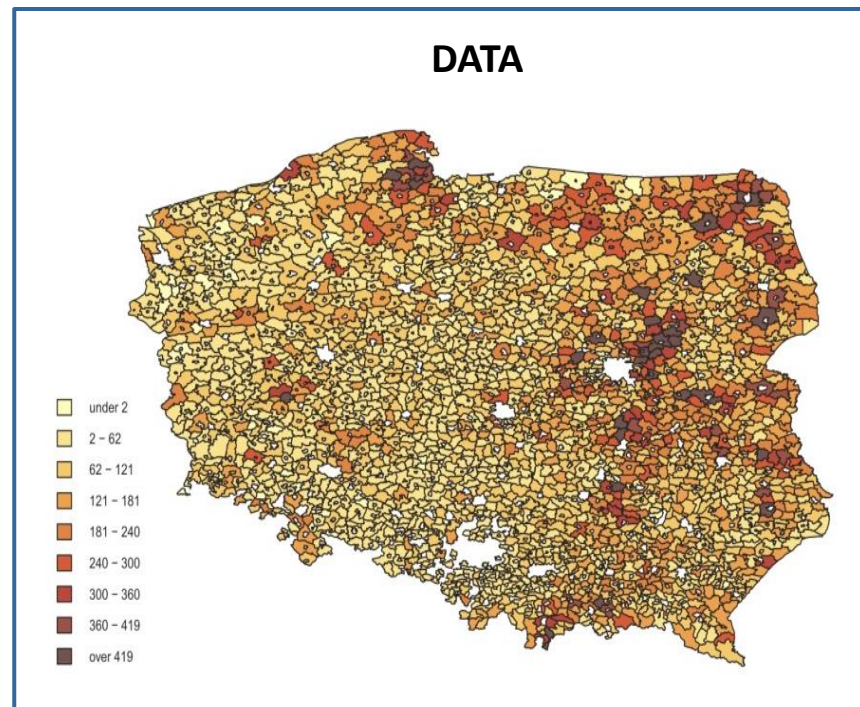
Model CAR



NAIVE prediction – proportional to population



DATA



Residuals from predicted values

Model CAR

NAIVE prediction



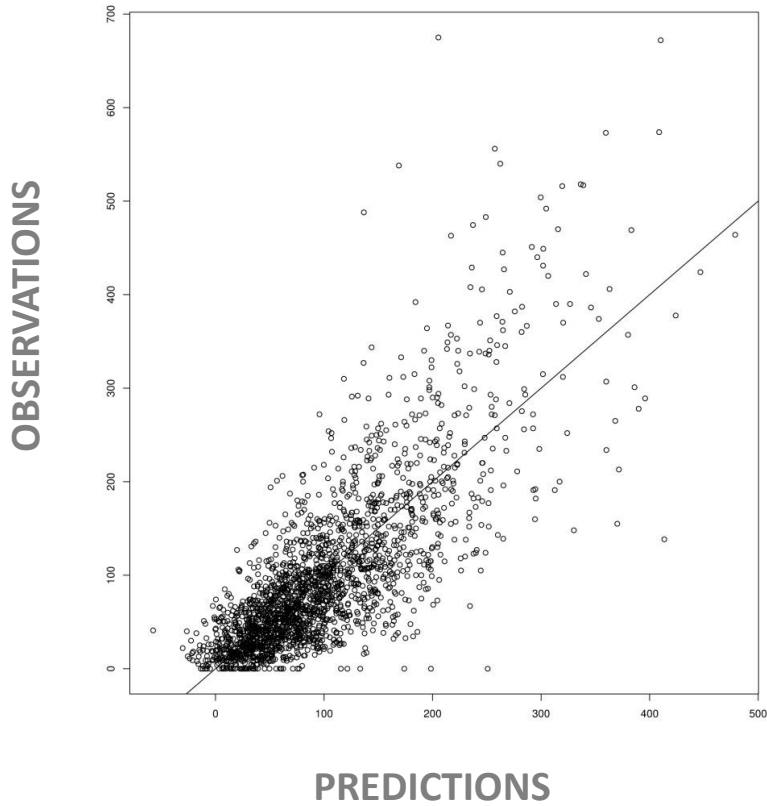
$$d_i = y_i - y_i^*$$

y_i - data
 y_i^* - prediction

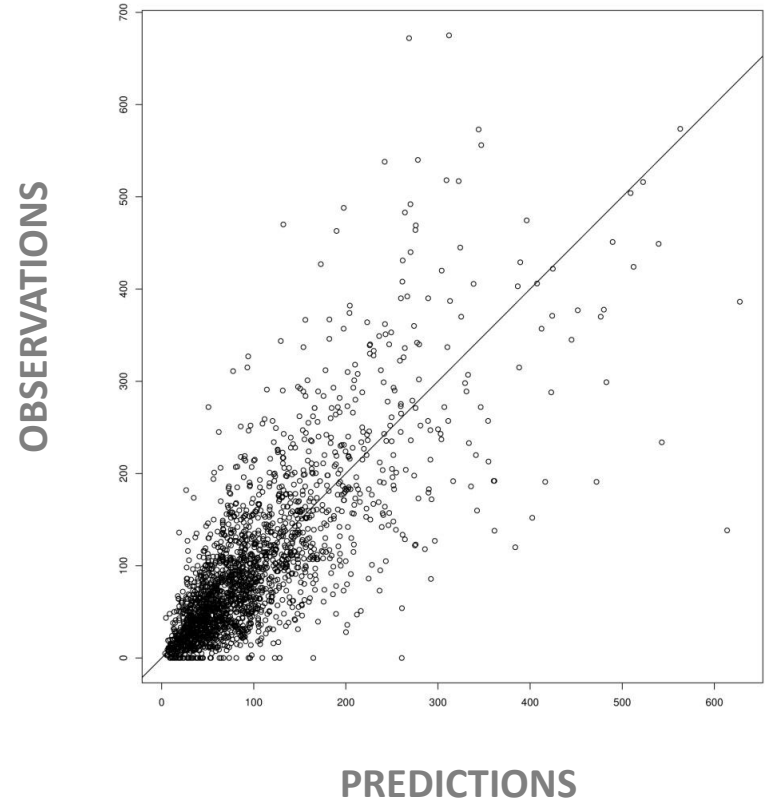
	MSE	Avg $ d_i $	Min(d_i)	Max(d_i)	r
CAR	3069.4	38.37	-275	469	0.784
Naive	3374.4	38.17	-475	403	0.766
LM	5641.2	51.28	-357	522	0.555

Scatterplots of data vs. predictions

Model CAR



NAIVE prediction



Modification #1: Various regression models in regions

$l=1, \dots, L$ index regions, e.g. voivodships, $n = \sum_{l=1}^L n_l$

\mathbf{X}^* - block diagonal matrix of covariates

Separate sets of regression coefficients and variance $\sigma^2_{Y,l}$ for each voivodship

$$\mathbf{X}^* = \left[\begin{array}{cccc|ccc} 1 & x_{11}^1 & \cdots & x_{1k}^1 & & & \\ \vdots & & \ddots & \vdots & & & \\ 1 & x_{n_1 1}^1 & & x_{n_1 k}^1 & & & \\ \hline & & & & \ddots & & \\ \hline & & & & & 1 & x_{11}^L & \cdots & x_{1k}^L \\ & & & & & & \ddots & \vdots & \\ & & & & & 1 & x_{n_L 1}^L & & x_{n_L k}^L \end{array} \right] \quad \boldsymbol{\beta}^* = \begin{bmatrix} \beta_0^1 \\ \vdots \\ \beta_k^1 \\ \hline \vdots \\ \beta_0^L \\ \vdots \\ \beta_k^L \end{bmatrix}$$

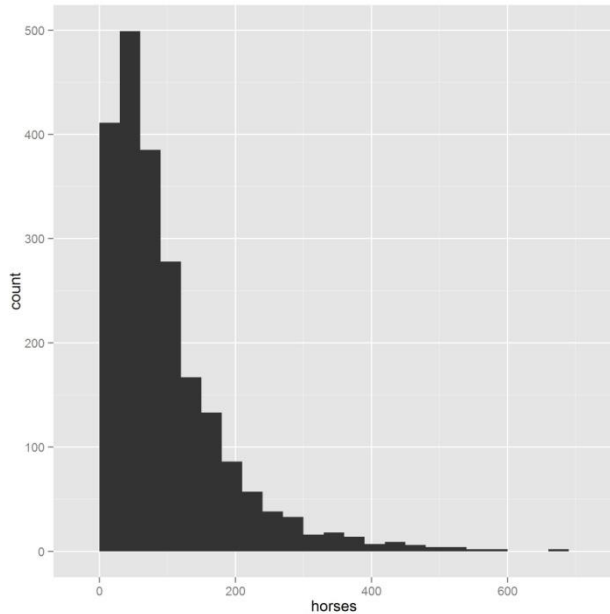
$$\boldsymbol{\mu} = \mathbf{X}^* \boldsymbol{\beta}^* + \boldsymbol{\epsilon},$$

$$\boldsymbol{\epsilon} \sim \text{Gau}_n(\mathbf{0}, \mathbf{N})$$

$$\tau^2(\mathbf{D} - \rho \mathbf{W})^{-1} = \mathbf{N}$$

	MSE	Avg $ d_i $	Min(d_i)	Max(d_i)	r
CAR	3069.4	38.37	-275	469	0.784
CAR*	3124.9	38.99	-256	446	0.783
Naive	3374.4	38.17	-475	403	0.766
LM	5641.2	51.28	-357	522	0.555

Modification #2: Accounting for data skeweness



Distributions of activity data (here: horses) are highly right skewed → the assumption of normality should be revised.

Potential approaches

- log transformation
- truncated normal distribution
- trans-Gaussian kriging
- ...

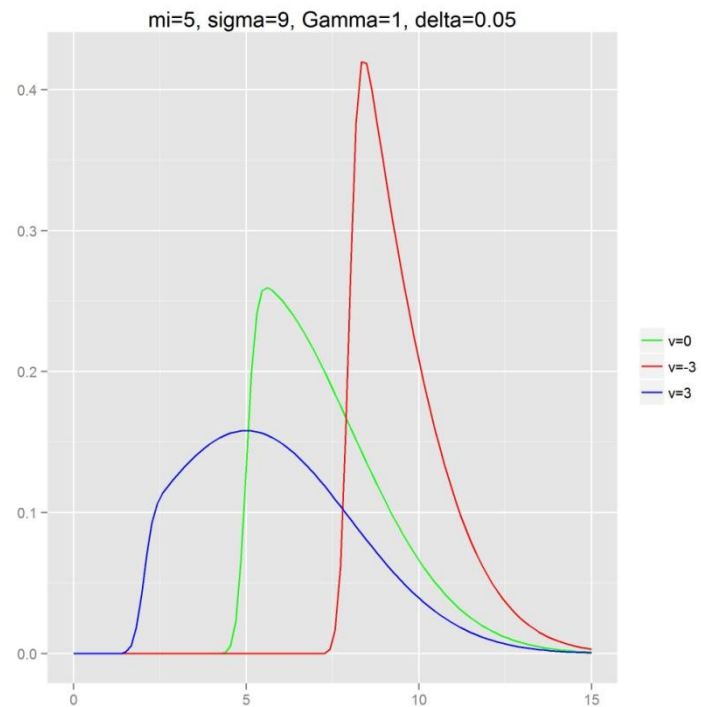
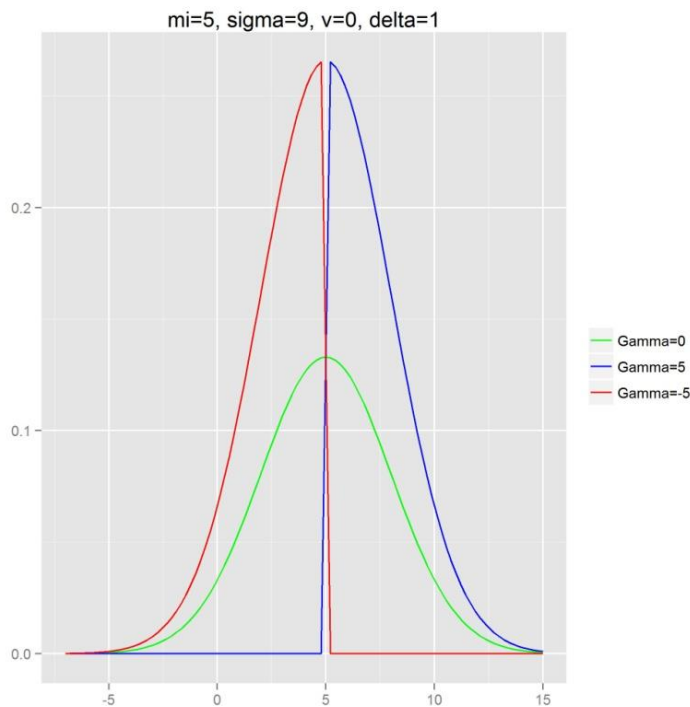
However, none of the listed options support summation of random variables
→ this is required in the developed model of spatial scaling (aggregation matrix $\mathbf{C}_{N \times n}$)

Closed skew normal (CSN) distribution

- Introducing skewness to the normal distribution, while the distribution is closed under marginalisation and conditioning (Dominiguez-Molina et al. 2003)
- Density of multivariate CSN distribution: $\mathbf{Y} \sim CSN_{p,q}(\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\Gamma}, \nu, \Delta)$

$$f_{p,q}(\mathbf{y} \mid \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\Gamma}, \nu, \Delta) = K \phi_p(\mathbf{y}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) \Phi_q(\boldsymbol{\Gamma}(\mathbf{y} - \boldsymbol{\mu}); \nu, \Delta)$$

where $K = \Phi_q^{-1}(0; \Delta + D\Sigma D^T)$, $\phi_p(\cdot)$ - standard normal pdf, $\Phi_q(\cdot)$ - standard normal cdf



Properties of closed skew normal distribution

- Closed under linear transformation (Gonzalez-Farias et al. 2004)

Let $\mathbf{Y} \sim \text{CSN}_{p,q}(\boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\Gamma}, \boldsymbol{\nu}, \boldsymbol{\Delta})$ and $A_{n \times p}$. Then

$$A\mathbf{Y} \sim \text{CSN}_{n,q}(\boldsymbol{\mu}_A, \boldsymbol{\Sigma}_A, \boldsymbol{\Gamma}_A, \boldsymbol{\nu}, \boldsymbol{\Delta}_A)$$

→ important for the disaggregation method

- Conditioning property → important for estimation (Gibbs sampler within MCMC)

Concluding remarks

We propose a novel approach for allocation of activity data to finer grids, conditional on available covariate information.

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- Good results for livestock activity data of **agricultural sector**, but very limited e.g. in residential sector (natural gas consumption in households)

The approach is applicable for **AREA emission sources** which are **spatially correlated**.

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We propose a novel approach for allocation of activity data to finer grids, conditional on available covariate information.

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The approach is applicable for **AREA emission sources** which are **spatially correlated**.

- The method is feasible for disaggregation from *districts* to *municipalities*, but not from *voivodeships* to *municipalities*.

Concluding remarks

We propose a novel approach for allocation of activity data to finer grids, conditional on available covariate information.

- Good results for livestock activity data of **agricultural sector**, but very limited e.g. in residential sector (natural gas consumption in households)

The approach is applicable for **AREA emission sources** which are **spatially correlated**.

- The method is feasible for disaggregation from *districts* to *municipalities*, but not from *voivodeships* to *municipalities*.
- Comparison with the naive (proportional) disaggregation:
In the case study, 9% improvement in terms of the *mean squared error*.

In general, it provides the assessment of the **significance of regression coefficients** and **uncertainty of calculated values**.

TAKE HOME MESSAGE:

A *structure of dataset* can give us an opportunity to develop an improved / alternative modeling approach, and thus to provide a better insight.



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Thank you for your attention!

