

Interim Report

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The Emergence of Altruistic Punishment: Via Freedom to Enforcement

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The emergence of altruistic punishment: via freedom to enforcement

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Faculty of Mathematics, University of Vienna, A-1090 Vienna, Austria e-mail: karl.sigmund@univie.ac.at, phone: +43 (0)1 4277 506 12, fax: +43 (0)1 4277 9 506 In human societies, cooperative behaviour in public goods interactions is usually enforced through institutions that impose sanctions on free-riders. Many experiments on public goods games have shown that in the absence of such institutions, individuals are often willing to punish defectors, even at a cost to themselves, effectively 'taking the law into their own hands'¹⁻¹¹. Theoretical models confirm that social norms prescribing the punishment of deviant behaviour are stable: once established, they prevent invasion by dissident minorities¹²⁻¹⁵. But how can such costly punishing behaviour gain a foothold in the population? A surprisingly simple model shows that if individuals have the option to stand aside and abstain from the public goods interaction, this paves the way for the emergence and establishment of cooperative behaviour based on the punishment of defectors. Thus the freedom to withdraw from the public enterprise leads to a self-enforcing prosocial norm. Paradoxically, the option of individual autarky may be an important step for the emergence of institutions punishing the non-cooperation of their members. Conversely, public goods interactions which are obligatory rather than voluntary are unlikely to gain a foothold in the population.

An impressive body of evidence shows that many humans are willing to pay a personal cost in order to punish wrong-doers^{1–10}. In particular, punishment is a very effective mechanism to ensure cooperation in public goods interactions. All human populations seem willing to use costly punishment to varying degree, and their willingness to punish correlates with the propensity for altruistic contributions¹¹. This raises an evolutionary problem: in joint enterprises, free-riding individuals who do not contribute, but exploit the public goods, fare better than those who pay the cost of contributing. If successful behaviour spreads, these defectors will eventually take over, until there is nothing left to exploit. Punishment is costly, it also reduces the punishers' payoff. This raises what has been called a 'second order social dilemma'. Costly punishing is an altruistic act. Individuals who contribute, but do not punish, are better off than the punishers. The frequency of punishers will dwindle and the defectors return.

This second order defection can be punished in turn, and prevented to spread. Thus a freeriding minority will be seriously harmed in the case of altruistic punishment (while it will be pampered in the case of altruistic cooperation). Any social norm that includes the rule to punish those who deviate is evolutionarily stable: once established, it cannot be displaced by an invading minority of dissidents¹². But how can such punishing behaviour gain a foothold in the population? The trait has to be rare, initially, and thus will incur huge costs by ceaselessly punishing. The emergence of altruistic punishing behaviour is acknowledged to be a major puzzle in the evolution of cooperation. "We seem to have replaced the problem of explaining cooperation with that of explaining altruistic punishment"¹⁶.

We will show that the puzzle disappears if one assumes that individuals can voluntarily decide whether to take part in the joint enterprise or not. If they do not participate, they can obtain an autarkic payoff independent of the other players' behaviour. Thus we consider four strategies. The *loners* are those who do not participate in the public enterprise (they need not be solitary individuals: they just abstain from the public goods game). Those who participate include the *defectors*, who do not contribute but exploit the contributions of the others; the *cooperators*, who contribute, but do not punish; and the *punishers*, who not only contribute to the public good, but punish the defectors, and possibly also those who fail to punish the defectors. In such a model, punishers will invade and take over. In the absence of the loner's option, however, they will often not be able to invade, and the population will be dominated by defectors. This means that if participation in the joint enterprise is voluntary, cooperation-enforcing behaviour emerges. If participation is obligatory (i.e. loners are excluded), then the defectors will win.

This intriguing result was originally presented by Fowler¹⁷. But his argument was based on a model with serious shortcomings, which does not justify the conclusions¹⁸. Here we propose a model vindicating Fowler's intuition. If individual autarky is an option, social norms enforcing cooperation through punishment will emerge and come close to fixation, whereas obligatory participation in the public goods game leads to take-over by defectors. These theoretical find-

ings agree well with the results of recent experiments, and may offer a solution to one of the most persistent problems in the evolution of cooperation.

We consider a well-mixed population of constant size M. From time to time, a random sample of size N is selected and offered the option to participate in a public goods game. Those who agree to do so can decide whether or not to contribute an investment of value c to themselves. The individual contributions are added up and multiplied with a factor r > 1. The resulting sum is then divided equally among all participants of the public goods game. After this interaction, each contributor can impose a fine β upon each defector, at a personal cost γ for each fine. Moreover, those who punish can also impose a fine on those who contributed, but failed to punish non-contributors. We shall assume for simplicity that for this second type of punishment, fines and costs are reduced by a factor α , with $0 \le \alpha \le 1$. By x we denote the total number of cooperators (who contribute in the public goods game but do not punish), by ythat of defectors (who participate in the public goods game but do not contribute), by z that of loners (unwilling to participate) and by w the number of punishers (who contribute, and punish the defectors as well as the cooperators who did not punish the defectors in their group). Thus M = x + y + z + w. We do not consider more complex strategies (basing their decision, for instance, on the size and composition of the group, or on past experience).

Each loner receives a constant payoff σ . Among the random sample of size N, there will be N_x cooperators, N_y defectors, N_z loners and N_w punishers. These are random variables distributed according to a multivariate distribution which describes sampling without replacement. The group of those willing to participate in the public goods game has size $S := N_x + N_y + N_w$. If $S \leq 1$ then the public goods game does not take place. A player who volunteered for it receives the loner's payoff σ . If S > 1, each participant of the public goods game obtains an income $r(N_x + N_w)c/S$. The payoff for the contributors (i.e. the cooperators and the punishers) is reduced by c. The payoff for the defectors is reduced by βN_w . The payoff for the cooperators is reduced by $\alpha\beta N_w$, provided $N_y > 0$ (if there are no defectors in the group, non-punishing behavior will go unnoticed). The payoff for punishers is reduced by γN_y and, if $N_y > 0$, by $\alpha \gamma N_x$.

This concludes the description of the strategic interaction¹⁸. We next specify how strategies are transmitted within the population¹⁹. We define each players' fitness as 1-s+sP, the convex combination of the 'baseline fitness', which is normalised to 1 for all players, and the payoff P from the optional public goods game with punishment. The relative importance of each component is determined by the selection strength s: small s means weak selection. We shall assume that occasionally, a randomly chosen player can change strategy by adopting the strategy of a player picked with a probability proportional to that player's fitness. This mimics a learning process similar to the Moran process describing natural selection: more successful players are copied more frequently. In addition, we shall assume that with a small probability μ , a player can switch to another strategy irrespective of its payoff (this "mutation term" corresponds to blindly experimenting with anything different).

The analysis of the corresponding stochastic dynamics is greatly simplified in the limiting case $\mu \to 0$. The population consists almost always of one or two types at the most. This holds because for $\mu = 0$ the four monomorphic states are absorbing, and for very small μ the fate of a mutant (i.e. its elimination or fixation) is settled before the next mutant appears. The probabilities ρ_{ij} that a single *i*-player in a population of *j*-players reaches fixation can be calculated for $i, j \in \{x, y, z, w\}$ (see online supporting material). This defines a transition matrix among the four monomorphic states of the system, and hence a unique stationary distribution. For small mutation rates μ , this distribution specifies how likely the system is to be in the corresponding pure state, or in its vicinity. Computer simulations show that the approximation also holds for larger mutation rates (on the order of 1/M).

The outcome is striking: in the limit of rare mutations, the system is most of the time in the homogeneous state with punishers only, irrespective of the initial composition of the population. For large populations (M = 1000 can be considered large for most of our prehistory) and small mutation rates, the system spends more than 80 percent in or near the punisher state. This prevalence diminishes only for very small selection strengths (Fig. 1).

In the case of an obligatory public goods game, i.e. in the absence of the loner's option, the situation is very different: in the limit of rare mutations, the system spends most of the time in or near the state with defectors only. For the same parameter values as before, the state is for 90 percent of the time dominated by defectors, and there is hardly any economic benefit from the public good (Fig. 2a). If all contributors punish (i.e. cooperators are excluded), the result remains essentially the same: even if defectors prevail for obligatory public goods games, they are eliminated if the public goods game is voluntary.

Volunteering in the absence of the punishment leads to a more cooperative outcome than for the obligatory game but not to the fixation of the cooperative state. The system exhibits a strong tendency to cycle (from cooperators to defectors to loners and back to cooperators). Roughly speaking, almost half of the time the state is dominated by loners. An outcome dominated by cooperators is almost as likely, whereas domination by defectors is relatively rare. In the limiting case of weak selection, the population even cooperates most of the time (Fig. 2b).

Whereas the limiting case of small mutation rates can be studied analytically (c.f. Figs. 1, 2, and the supplementary information), the case of substantial mutation rates can only be handled by numerical simulations. Complementing interactive online tutorials are provided at *http://homepage.univie.ac.at/hannelore.brandt/publicgoods/* and the VirtualLabs at *http://www.univie.ac.at/virtuallabs*. These show that the outcome is robust within a wide range of parameter values. With cooperators, loners and defectors only, the latter do worst, whereas the former two perform comparably well. With cooperators, punishers and defectors, but no loners, punishers do not prevail, except for large mutation rates. In that case, the mutational drift supplying defectors keeps the punishers active and prevents them from being undermined by cooperators. If all four types are admitted, punishers prevail.

In an obligatory public goods game with cooperators and defectors only, the latter obviously win. The loner's option allows cooperators to persist (although they cannot dominate for a substantial period). The reason is a simple rock-paper-scissors mechanism^{20–22}. If there are many defectors, loners will spread. When loners abound, many of the random samples will

result in only small groups of players willing to participate. If the groups are sufficiently small, the average payoff for cooperators will be larger than that for defectors, despite the fact that within each group, the latter have a higher payoff than the former; it even pays for the individual defector to switch to cooperation. Thus if the group is sufficiently small (S < r), there is no social dilemma. This is a fleeting state only: quickly, cooperators spread, group size increases and the social dilemma returns. But the recurrent eclipse of the social dilemma allows punishers eventually to step in and take over (see Fig. 3).

We have assumed in our model that a punisher faced with twice as many defectors metes out twice as many fines. This assumption can be modified without affecting the conclusions. As it stands, it makes the life of a rare punisher particularly difficult. It is all the more remarkable that punishers can invade nevertheless.

Whether cooperators who fail to punish are punished or not plays a surprisingly small role. The parameter α has little influence on the numerical simulations, and does not show up in the formulas (see supplementary information). The reason is that in the limiting case (μ very small), the three types of punishers, cooperators and defectors rarely co-exist: hence punishers cannot hold cooperators to account for not punishing defectors. In the case $\alpha = 0$, the second order social dilemma always holds: punishing is costly, and contributors failing to punish can get away with it. Nevertheless, punishing behaviour can emerge and prevail, because the first order social dilemma occasionally breaks down. It is of interest in this context that experimental evidence for the punishment of non-punishers (i.e. for non-vanishing α) seems to be lacking ¹³.

For weak selection, an analytical condition for the dominance of punishers in the absence of loners can be derived: $3(N - r) < N(N - 1)(\beta - \gamma)$ (see supplementary information). This condition is satisfied in Fig. 2a and is reflected in the dominance of punishers for small s. Moreover, if defectors are allowed to retaliate (in which case β is as large as γ) punishers never dominate the population and loners are needed to establish cooperation. However, also note that for strong selection it is clear that defectors always dominate because selection acts against invasion attempts of cooperators as well as punishers (see Fig. 3 and supplementary information).

We could also assume that punishers penalise non-participants. The fine could be $\delta\beta$ and the cost to the punisher $\delta\gamma$, with $0 \le \delta \le 1$. Again, this has no great effect on the outcome. If loners are frequent, many samples will contain no punisher. If punishers are frequent, defectors are kept in check and non-participants do poorly, with or without being punished. The most significant difference seems to be that if punishers pay a heavy cost for penalising loners (high δ and γ), then cooperators are needed to overcome the dominance of loners and catalyse the take-over by punishers.

Differences between first and second order social dilemma have been pointed out before in a model¹⁴ based on a group selection scenario and exploiting the fact that when punishers are common, individual level selection against them is weak and may be overcome by selection among groups. Several other models confirm that the punishment of defectors is stable, if it is the prevalent norm. For example by assuming some degree of conformism in the population¹⁵: individuals preferentially copy what is frequent. Similarly, cooperation can also be stabilised through indirect reciprocity²³, but in each of these cases, the emergence of the pro-social norm remains unclear^{24,25}.

Our model, in contrast, shows that even when initially rare, punishing behaviour can be selectively advantageous, and is likely to become fixed. We consider the most challenging scenario, namely a single well-mixed population whose members imitate preferentially what fares better, not what is more common. The effects of group selection and conformist transmission will further the maintenance of this pro-social norm, once it is established.

The spread of initially rare punishers is also the outcome in Ref. 14. But that model, based on an infinitely large population, assumes that single cooperators can play the public goods game, and obtain a payoff which is higher than that of loners (as high, in fact, as if the whole population contributes to the public good). This neglects the fact that contributing to a public goods game is a risky investment whose return depends on what other players are doing. By contrast, our model leads, in the limiting case of an infinitely large population, to a bistable outcome¹⁸. Depending on the initial condition, the state either ends up in a Nash equilibrium consisting of cooperators and punishers only, or leads to endless oscillations of loners, defectors and cooperators, without any punishers. Bistability also holds for the reputation-based model ²⁶. Both approaches do not favour the spread of a minority of punishers. Their emergence is boosted, in finite populations, by stochastic effects. Voluntary participation, by reducing group size if defectors abound, promotes these stochastic effects.

Recent experiments show that if players can choose between joining a public goods game either with or without punishment, they prefer the former²⁷. The interpretation seems clear: whoever freely accepts that defection is punished is unlikely to be a defector. It is thus less risky to join such a group. Players voluntarily commit themselves to sanctioning rules. This voluntary submission to a sanctioning regime is not always immediate, however: in the majority of cases it requires a few preliminary rounds. Many players appear to have initial reservations against a sanctioning regime and need a learning phase. In another series of experiments, it has been shown that threatened punishment can decrease the level of cooperation in trust games²⁸. Moreover, players reduce their punishing behaviour if they have a less costly option (such as excluding defectors from indirect reciprocity networks), but they do not give it up: rather, they punish in a more focussed way²⁹. Experimental evidence for altruistic punishment can also be found in the ultimatum game (rejecting an unfair offer is costly to both players)² and in indirect reciprocity (by not helping defectors, players reduce their own chances of being helped)³⁰.

Reports from present-day hunter-gatherer societies often stress their egalitarian and 'democratic' features: individuals have a great deal of freedom³¹. This creates favourable conditions for voluntary participation. Opting for the 'loner' strategy does not mean living an eremit's life; it means not participating in a collective hunt, for instance, but collecting mushrooms instead. On the other hand, ostracism was probably an early form of severe punishment. There seems to be a smooth transition between choosing not to take part in a joint enterprise and being excluded from it. Together, these two alternatives may explain the emergence of rule-enforcing institutions promoting pro-social behaviour - following Hardins recipe for overcoming the *tragedy of* *the commons*: mutual coercion, mutually agreed upon³². However, we must emphasise that there are public good games where no one can stand aside: the preservation of our climate is one example³³. In such games, participation is obligatory – and defection widespread.

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Figures



Hauert et al. - Figure 1

Figure 1: Punishment and abstaining in public goods games in finite populations. In the limit of rare mutations ($\mu \rightarrow 0$), the dynamics is restricted to transitions between the four homogeneous states with all cooperators (blue), defectors (red), loners (yellow) or punishers (green). The two panels depict the probabilities of each state as a function of the selection strength s for population sizes M = 100 (a) and M = 1000 (b). Simulation data for small mutation rates confirms the analytical results (colored dots). In contrast to the analysis, the fitness of individuals in the simulations is determined by a single random interaction rather than the average. This is source of stochasticity and, together with the mutation rate, is responsible for the small differences between analytical results and the simulation data. Parameters: $N = 5, r = 3, \sigma = 1, \gamma = 1, \beta = 2, \alpha = 0.1, s_{max} = 0.151$; Simulations: a mutation rate $\mu = 10^{-4}$, sampling time $T = 10^7$, b $\mu = 10^{-3}$, $T = 10^6$.



Figure 2: Punishment in obligatory public goods games (a) and voluntary participation in public goods games without punishment (b). In the limit of rare mutations, the dynamics reduces to transitions between homogeneous states with all cooperators (blue), defectors (red), punishers (green) or loners (yellow). The probabilities for each state are shown as a function of the selection strength *s*. In the limit of neutral evolution (s = 0) the strategic differences disappear and all three respective states become equally likely. In a the system is usually found in a state with all defectors, except for weak selection where punishers manage to get the upper hand. In contrast, in **b**, the system spends significantly more time in the cooperator or loner states than in the defector state. Parameters: $N = 5, r = 3, \sigma = 1, \gamma = 1, \beta = 2, \alpha = 0.1, M = 100$; a $s_{max} = 0.151$; b $s_{max} = 0.714$.



Figure 3: Schematic dynamics for a obligatory public goods games with punishment, **b** voluntary public goods games, and **c** the combined effects of volunteering and punishment in finite populations. In the limit of rare mutations, the dynamics is reduced to transition probabilities between the homogeneous states with all cooperators (C), defectors (D), loners (L) or punishers (P). The three panels depict all transition probabilities > 0.01% together with the relative time τ spent in each state for maximal selection strength. **a** In the absence of loners, defectors dominate despite punishment. The cooperator and punisher state are connected by a neutral edge with a transition probability of 1/M in either direction (dashed line). The defector state is essentially stable with transition probabilities to the cooperators state of $< 10^{-4}$ and still many orders of magnitude smaller to reach the punisher state. **b** In voluntary public goods games the transition probabilities illustrate the cyclic dominance of the three strategies and illustrate that the system spends little time in the defector state because of the large transition probability D \rightarrow L. **c** Combining the two mechanisms illustrates the pivotal role of loners where the system can embark on another cooperator-defector-loner cycle or switch to the punisher state. Parameters: $N = 5, r = 3, \sigma = 1, \gamma = 1, \beta = 2, M = 100, s = 0.151$.